

L Number	Hits	Search Text	DB	Time stamp
17	14	"variable angle prism" NEAR7 advantag\$4	USPAT; US-PGPUB; EPO; JPO; IBM_TDB	2003/07/01 12:20
20	0	("200100141741").PN.	USPAT; US-PGPUB; EPO; JPO; IBM_TDB	2003/07/01 12:18
21	0	(2001/00141741).CCLS.	USPAT; US-PGPUB; EPO; JPO; IBM_TDB	2003/07/01 12:18
22	0	("US200100141741").PN.	USPAT; US-PGPUB; EPO; JPO; IBM_TDB	2003/07/01 12:18
23	0	(US2001/00141741).CCLS.	USPAT; US-PGPUB; EPO; JPO; IBM_TDB	2003/07/01 12:18
24	0	"2001/00141741"	USPAT; US-PGPUB; EPO; JPO; IBM_TDB	2003/07/01 12:18
25	0	"200100141741"	USPAT; US-PGPUB; EPO; JPO; IBM_TDB	2003/07/01 12:18
26	188	Iijima-\$.IN.	US-PGPUB	2003/07/01 12:20
31	25	(@ad<19980908 OR @rlad<19980908) AND (348/207.99-376).CCLS. AND (two NEAR7 "angular velocity")	USPAT; US-PGPUB; EPO; JPO; IBM_TDB	2003/07/01 12:47
32	1	(@ad<19980908 OR @rlad<19980908) AND (348/207.99-376).CCLS. AND (parallel NEAR7 "angular velocity")	USPAT; US-PGPUB; EPO; JPO; IBM_TDB	2003/07/01 12:48
33	269	(@ad<19980908 OR @rlad<19980908) AND (parallel NEAR7 "angular velocity")	USPAT; US-PGPUB; EPO; JPO; IBM_TDB	2003/07/01 12:50
34	21	(@ad<19980908 OR @rlad<19980908) AND (parallel NEAR7 "angular velocity sensor")	USPAT; US-PGPUB; EPO; JPO; IBM_TDB	2003/07/01 12:51
-	859	SATO-YASUHIRO.IN. OR KITAGUCHI-TAKASHI.IN.	USPAT; US-PGPUB; EPO; JPO; IBM_TDB	2003/06/27 18:29
-	13	(SATO-YASUHIRO.IN. OR KITAGUCHI-TAKASHI.IN.) AND ccd	USPAT; US-PGPUB; EPO; JPO; IBM_TDB	2003/06/27 18:32
-	21	(SATO-YASUHIRO.IN. OR KITAGUCHI-TAKASHI.IN.) AND shak\$3	USPAT; US-PGPUB; EPO; JPO; IBM_TDB	2003/06/27 18:33
-	1	("4734726").PN.	USPAT; US-PGPUB; EPO; JPO; IBM_TDB	2003/06/30 10:41
-	6	(@ad<19980908 OR @rlad<19980908) AND camera AND shak\$3.AB. AND ((rotat\$3 OR turn\$3) NEAR3 (ccd OR "image sensor" OR "image pickup" OR "image pick up" OR "imaging device" OR "image sensing" OR "imaging array" OR "pixel sensor"))	USPAT; US-PGPUB; EPO; JPO; IBM_TDB	2003/06/30 11:40

-	3	((@ad<19980908 OR @rlad<19980908) AND camera AND shak\$3.AB. AND ((rotat\$3 OR turn\$3) NEAR3 (ccd OR "image sensor" OR "image pickup" OR "image pick up" OR "imaging device" OR "image sensing" OR "imaging array" OR "pixel sensor"))) AND "angular velocity"	USPAT; US-PGPUB; EPO; JPO; IBM_TDB	2003/06/30 10:54
-	17	(@ad<19980908 OR @rlad<19980908) AND camera AND shak\$3.AB. AND ("angular velocity" SAME "low pass")	USPAT; US-PGPUB; EPO; JPO; IBM_TDB	2003/06/30 12:13
-	9	(@ad<19980908 OR @rlad<19980908) AND camera AND shak\$3.AB. AND "20 Hz"	USPAT; US-PGPUB; EPO; JPO; IBM_TDB	2003/07/01 11:56
-	1	("5649237").PN.	USPAT; US-PGPUB; EPO; JPO; IBM_TDB	2003/06/30 12:02
-	1	("5172233").PN.	USPAT; US-PGPUB; EPO; JPO; IBM_TDB	2003/06/30 12:02
-	38	(@ad<19980908 OR @rlad<19980908) AND (348/207.99-376).CCLS. AND shak\$3.AB. AND "optical axis"	USPAT; US-PGPUB; EPO; JPO; IBM_TDB	2003/06/30 12:19
-	28	(@ad<19980908 OR @rlad<19980908) AND (348/207.99-376).CCLS. AND shak\$3.AB. AND ("optical axis" SAME ("angular velocity" OR sens\$3 OR detect\$3))	USPAT; US-PGPUB; EPO; JPO; IBM_TDB	2003/06/30 13:08
-	367	(@ad<19980908 OR @rlad<19980908) AND (348/207.99-376).CCLS. AND ("optical axis" NEAR9 ("angular velocity" OR sens\$3 OR detect\$3))	USPAT; US-PGPUB; EPO; JPO; IBM_TDB	2003/06/30 13:12
-	49	(@ad<19980908 OR @rlad<19980908) AND (348/207.99-376).CCLS. AND ("optical axis" NEAR9 ("angular velocity" OR detect\$3))	USPAT; US-PGPUB; EPO; JPO; IBM_TDB	2003/06/30 14:11
-	1	AND (shak\$3 OR handshak\$3) ("5649237").PN.	USPAT; US-PGPUB; EPO; JPO; IBM_TDB	2003/07/01 12:18
-	3	(@ad<19980908 OR @rlad<19980908) AND (348/207.99-376).CCLS. AND (pair NEAR7 "angular velocity")	USPAT; US-PGPUB; EPO; JPO; IBM_TDB	2003/07/01 12:44